

**informs** ANNUAL MEETING | 2020 VIRTUAL



## **Real-time Rolling Stock and Timetable Rescheduling in Urban Rail Networks: A Branch-and-Price Approach**

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**Introduction of this study**

**Mathematical model formulations**

**Solution methodologies**

**Conclusion**

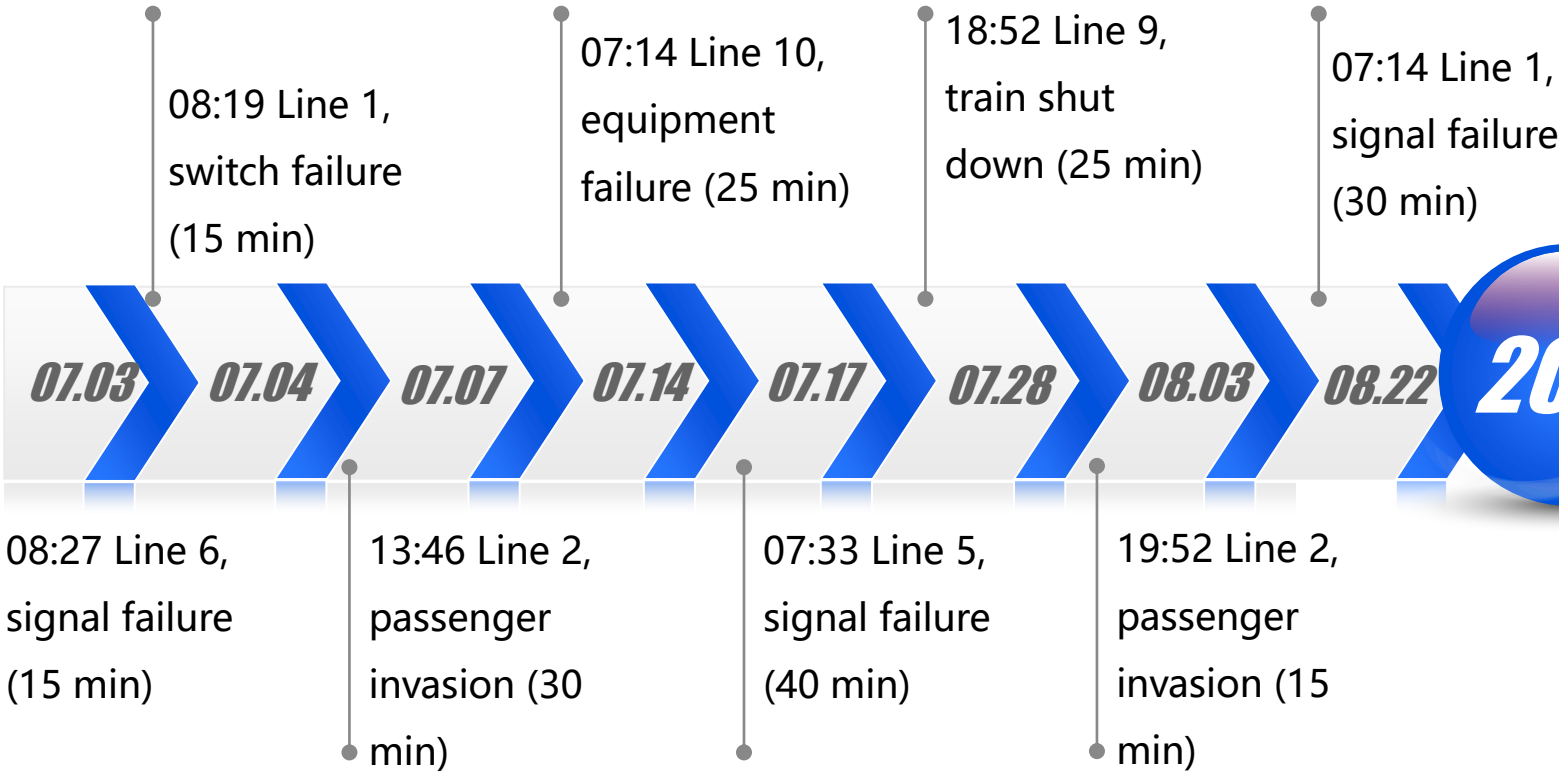


# Introduction

- **Urban metro system** (or rapid transit) is a passenger railway system in an urban area with **high capacity and frequency**.  
([Wikipedia](#))
- Since the first metro line London Metropolitan Railway was put into use in **1863**, urban metro systems have been widely established throughout the world in many large cities.
- During the **COVID-19 pandemic**, urban rail transit systems in China undertake great pressure to keep the crowdedness to avoid the spread of virus.



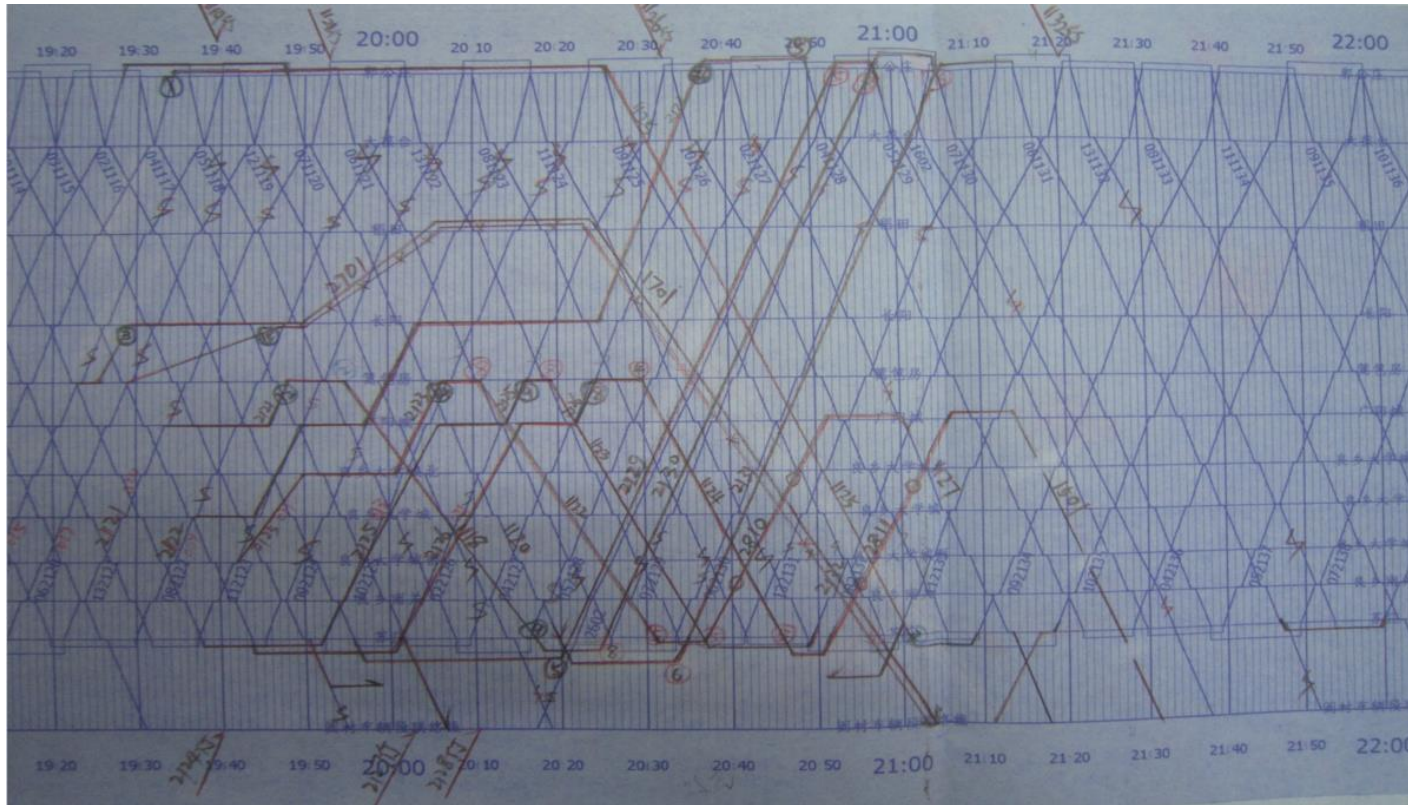
## ■ A large number of incidents happen in high-density metro systems



More than 60 incidents occur between Jul. to Aug.





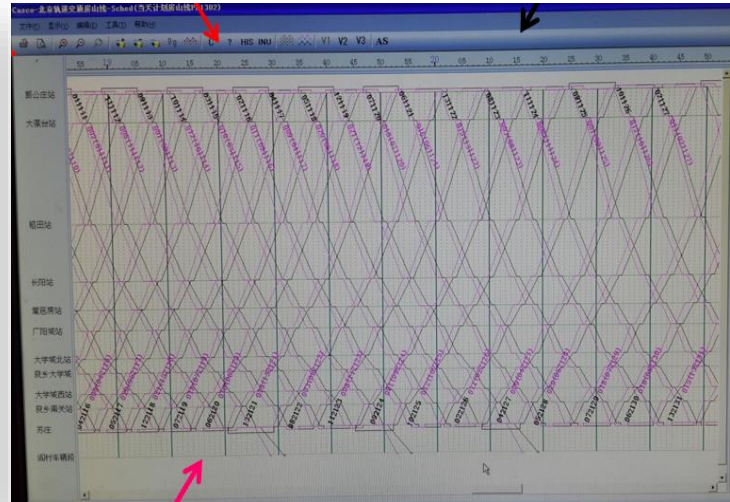


A real-world case of metro train rescheduling in Beijing subway



- Modern urban metro systems

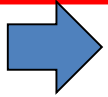
- Modern urban metro systems





# Literature review

Train  
timetable  
rescheduling



Rolling stock  
rescheduling

- Job-shop scheduling model
  - **Drawback:** Big-M and large LP gap
- Branch-and-bound
- Benders decomposition
- Metaheuristics
- Time-indexed formulation
  - **Drawback:** large-number of integer variables
- Lagrangian relaxation
- Event-activity formulation
  - **Drawback:** large-number of binary variables with Big-M
- Branch-and-cut

- Most existing methodologies focus on **mainline railways** and require **several minutes** of computational time



# Contribution

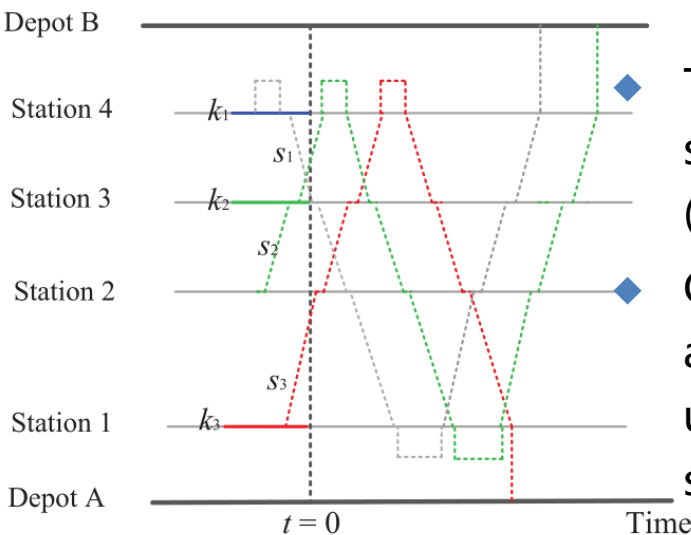
- We first propose a **path-based formulation** for the integrated rolling stock and timetable rescheduling for urban rail systems
- We develop a branch-and-price approach for acquiring a near-optimal solution more efficiently
- Real-world case studies are conducted to illustrate the effectiveness of our approach



# Mathematical formulation

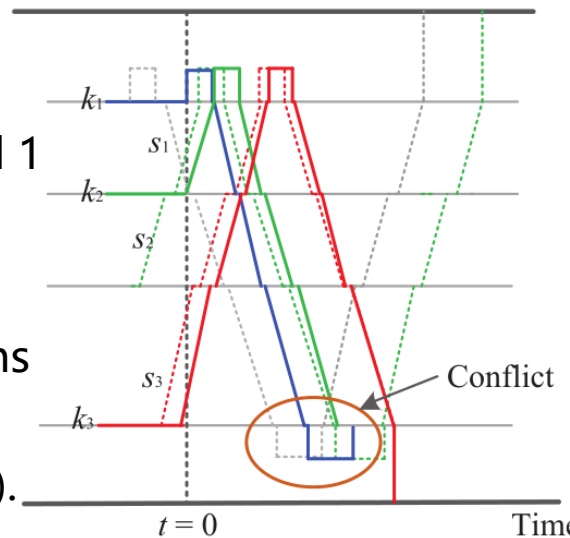
## Problem description

- We consider the train rescheduling problem for a **bi-directional urban rail corridor** with a set of stations (and depots) **I**.
- At the initial time  $t=0$ , the incident is resolved but the trains can no longer run to schedule.



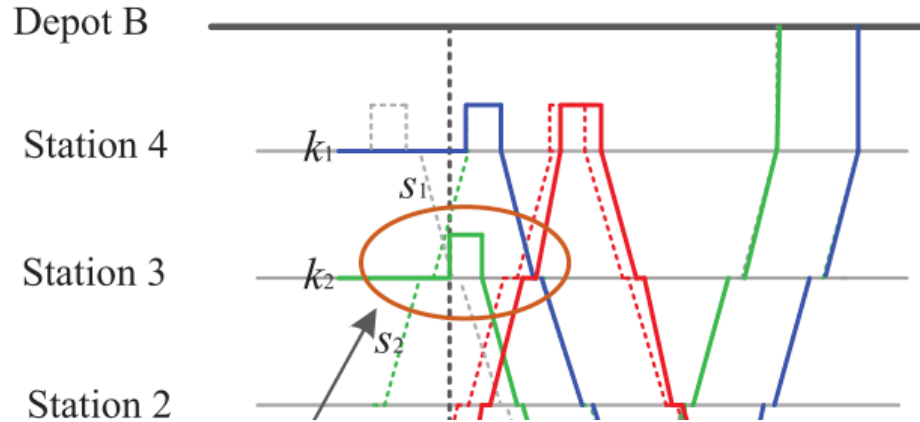
Three trains at station 4, 3 and 1 (Left).

Conflict may arise If the trains use existing schedule(Right).



- In practice, train dispatchers usually take four strategies to avoid conflict and reduce the negative effects for passengers, involving:

### C. Short-turning or add new trains



- The strategies are required to be generated in real-time and still dependent on human experiences
- In practice, only experienced dispatchers have the ability and access to reschedule train timetable



# Problem statement

- ◆ The issue can be modeled a mathematical optimization problem: Given a set of **K trains** located at stations and a **planned schedule** for each train, the aim is to generate a **new schedule** and **rolling stock circulation** plan for the trains (involving trains at depots), such that the delay of trains and canceling number of trains are minimized, with the following constraints satisfied:
  - Each train in the system must be assigned to a service or back to depot
  - Each service is covered at most one time
  - Train following headway should be kept within a limitation
  - At the end of time horizon (end of day), rolling stocks in each depot should be the same for the next day





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# Path-based formulation

- ◆ The problem can be considered by: finding a set of paths in the event-activity network (originated from each train at different stations), such that the total cost is minimized.

## Path-based formulation

$$\min_x \sum_{p \in P} c_p x_p \quad (3)$$

$$\text{s.t.} \quad \sum_{p \in P_k} x_p = 1, \quad \forall k \in K \quad (4)$$

$$\sum_{p \in P^e} x_p \leq 1, \quad \forall e \in E \quad (5)$$

$$\sum_{p \in \mathcal{P}} t_p^e x_p - \sum_{p \in \mathcal{P}} t_p^{e'} x_p \geq \left( \sum_{p \in \mathcal{P}} r_p^e x_p - 1 \right) \bar{t}_{e'} + \bar{h} \quad \forall (e, e') \in A \quad (6)$$

$$\sum_{p \in P} l_p^d x_p = N_d \quad \forall d \in D \quad (7)$$

$$x_p \in \{0, 1\}, \quad \forall p \in P \quad (8)$$



**Variable:**  $x_p$  if path  $p$  is selected in the rescheduled timetable

**Objective function:**

$$\begin{aligned} & \sum_{e \in E} q_e (1 - \sum_{p \in P} r_p^e x_p) + \sum_{e \in E} (\sum_{p \in P} t_p^e x_p - \hat{t}_e) \\ &= \sum_{e \in E} q_e - \sum_{e \in E} \hat{t}_e + \sum_{e \in E} \sum_{p \in P} t_p^e x_p - \sum_{e \in E} \sum_{p \in P} q_e r_p^e x_p \end{aligned}$$



Reformulation

$$\begin{aligned} & \sum_{e \in E} \sum_{p \in P} t_p^e x_p - \sum_{e \in E} \sum_{p \in P} q_e r_p^e x_p \\ &= \sum_{p \in P} \sum_{e \in E} (t_p^e - q_e r_p^e) x_p \\ &= \sum_{p \in P} c_p x_p \end{aligned}$$

$q_e$  Penalty for canceling event  $e$

$r_p^e$  If path  $p$  covers event  $e$

$t_p^e$  Time of event  $e$  with path  $p$

$\hat{t}_e$  Planned time of event  $e$



## Constraints:

$$\sum_{p \in P_k} x_p = 1, \quad \forall k \in K$$

Every train must be assigned with a path  $p$

$$\sum_{p \in P^e} x_p \leq 1, \quad \forall e \in E$$

Each event  $e$  should be covered at most once

$$\sum_{p \in \mathcal{P}} t_p^e x_p - \sum_{p \in \mathcal{P}} t_p^{e'} x_p \geq \left( \sum_{p \in \mathcal{P}} r_p^e x_p - 1 \right) \bar{t}_{e'} + \bar{h} \quad \forall (e, e') \in A$$

$$\sum_{p \in P} l_p^d x_p = N_d \quad \forall d \in D$$

A minimum headway time should be guaranteed

$$x_p \in \{0, 1\}, \quad \forall p \in P$$

$P_k$  Set of paths from train  $k$

$P^e$  Set of paths that may cover event  $e$

$(e, e') \in A$  Set of event pairs

$\bar{h}$  Minimum headway

Number of rolling stocks at depot  $d$  should equal to  $N_d$



# Model property

- Enumerating the complete set of the service path  $P$  is intractable and impractical since the number of possible event sequences increases exponentially with the number of events (i.e., the planned schedule)
- In particular, due to the computational time requirement (within one minute), we herein develop a column generation framework based branch-and-price solution methodology to generate high-quality service paths





# Solution methodologies

- Model reformulation
- Define dual variables
- Define Restricted master problem and subproblems
- Column generation to generate paths
- Develop a branch-and-price framework



# (1) Rewritten constraints

$$\sum_{p \in P_k} x_p = 1, \quad \forall k \in K$$

$$\sum_{p \in P^e} x_p \leq 1, \quad \forall e \in E$$

$$\sum_{p \in \mathcal{P}} t_p^e x_p - \sum_{p \in \mathcal{P}} t_p^{e'} x_p \geq \left( \sum_{p \in \mathcal{P}} r_p^e x_p - 1 \right) \bar{t}_{e'} + \bar{h} \quad \forall (e, e') \in A$$

$$\sum_{p \in P} l_p^d x_p = N_d \quad \forall d \in D$$

$$x_p \in \{0, 1\}, \quad \forall p \in P$$

$$\sum_{p \in \mathcal{P}} l_{pee'} x_p \geq \bar{h} - \bar{t}_{e'}, \quad \forall (e, e') \in A$$

where  $l_{pee'} = t_p^e - \bar{t}_{e'} r_p^e - t_p^{e'}$ .



## (2) Calculate the dual cost

### Define dual variables

$\tau_k \ (k \in K)$

**Train-cover constraints**

$\pi_e \ (e \in E)$

**Event-cover constraints**

$\phi_{e,e'} \ ((e, e') \in A)$

**Headway constraints**

$\lambda_d \ (d \in D)$

**Rolling stock constraints**



## (2) Calculate the dual cost

- Reduced cost for path  $p$  is given by

$$\begin{aligned}\bar{c}_p &= c_p - \tau_k - \sum_{e \in E^p} \pi_e - \sum_{(e,e') \in A} l_{pee'} \phi_{e,e'} - \sum_{d \in D} l_p^d \lambda_d \\ &= \sum_{e \in E} (t_p^e - q_e r_p^e) - \tau_k - \sum_{e \in E^p} \pi_e - \sum_{(e,e') \in A} (t_p^e - \bar{t}_{e'} r_p^e - t_p^{e'}) \phi_{e,e'} - \sum_{d \in D} l_p^d \lambda_d \\ &= \sum_{e \in E} t_p^e - \sum_{e \in E^p} (\pi_e + q_e) - \sum_{(e,e') \in A} (t_p^e - \bar{t}_{e'} r_p^e - t_p^{e'}) \phi_{e,e'} - \sum_{d \in D} l_p^d \lambda_d\end{aligned}$$

- The pricing problem is to find a event sequence with a negative reduced cost ( $\bar{c}_p < 0$ ), which can be found by solving the following problem:

$$\min_{p \in P_k} \bar{c}_p$$



## (2) Calculate the dual cost

The above objective function can be reformulated as follows

$$\begin{aligned}\bar{c}_p &= \sum_{e \in E^p} [(1 - \phi_{e,e'})t_e - \pi_e - q_e + \bar{t}_{e'}\phi_{e,e'}] + \sum_{e \in E_p} (t(e)\phi_{e_f,e}) \\ &= \sum_{e \in E^p} [(1 - \phi_{e,e'})t_e - \pi_e - q_e + \bar{t}_{e'}\phi_{e,e'} + t(e)\phi_{e_f,e}] \\ &= \sum_{e \in E^p} (q_e t_e + \xi_e)\end{aligned}$$

where

$$q_e = 1 - \phi_{e,e'} + \phi_{e_f,e} \quad \xi_e = \bar{h}\phi_{e,e'} - \pi_e - q_e$$

**Minimizing the above problem is equivalent to finding a shortest path in the event network**





# Branch-and-price procedure

Then, we can use standard branch-and-price procedure:

- Generate initial solution (a set of paths by heuristic strategies)
- Solve restricted master problem (RMP)
- Solving pricing subproblems for each train  $k$
- Add the paths with negative cost to the RMP
- Stopping criteria: there is no path with negative cost; time exceeds the limit
- Branch on the LP relaxation, and iterate.

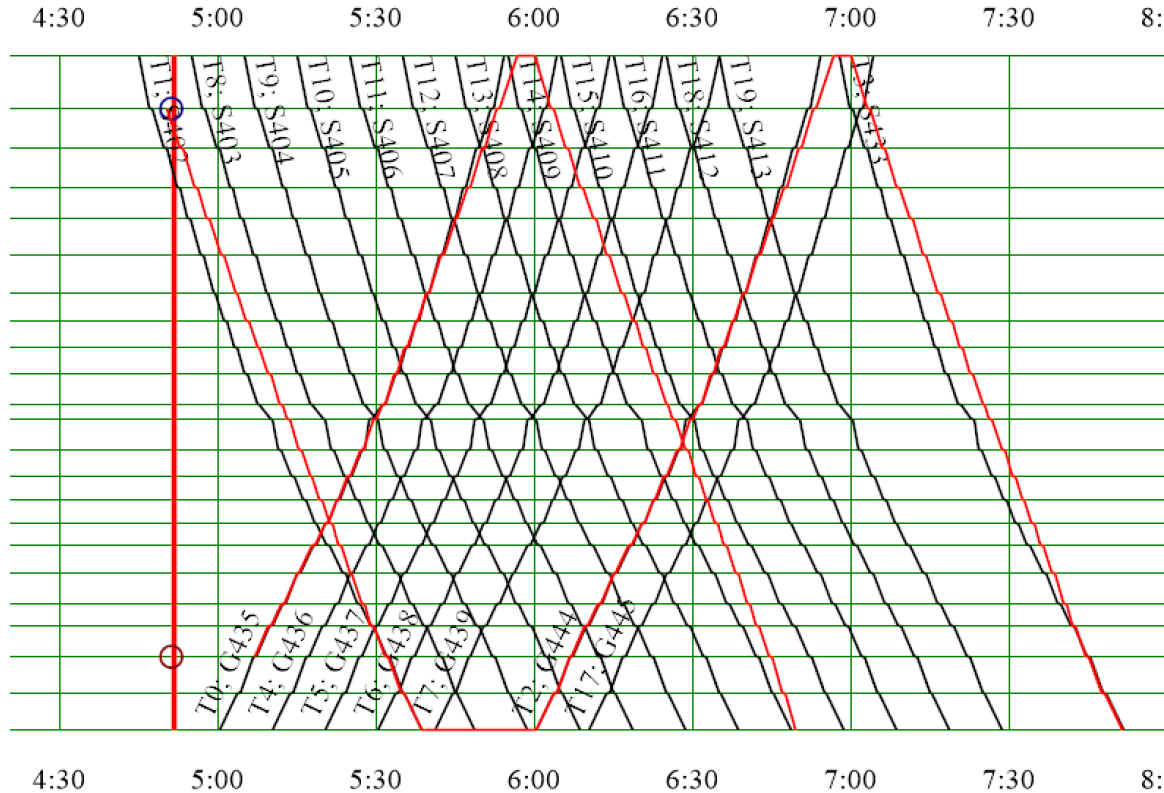


◆ We collaborated with Beijing subway and a signal company and developed a software embedded with our methodology (coded with C#).



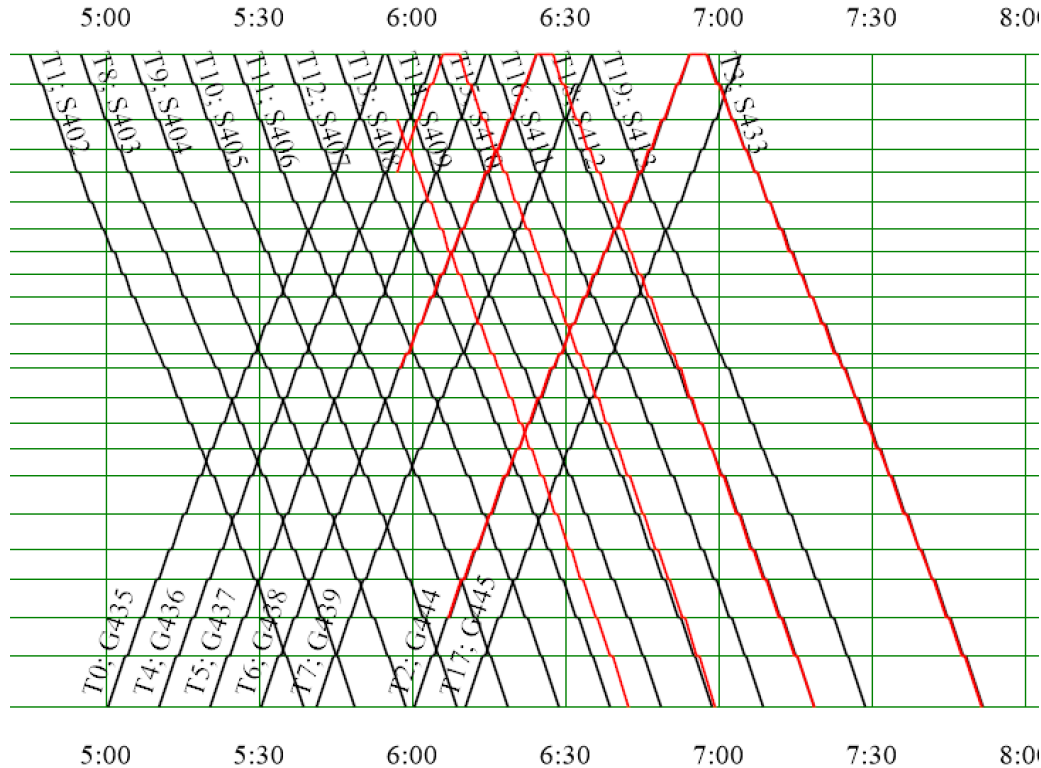
# Results and conclusions

## Some primarily results



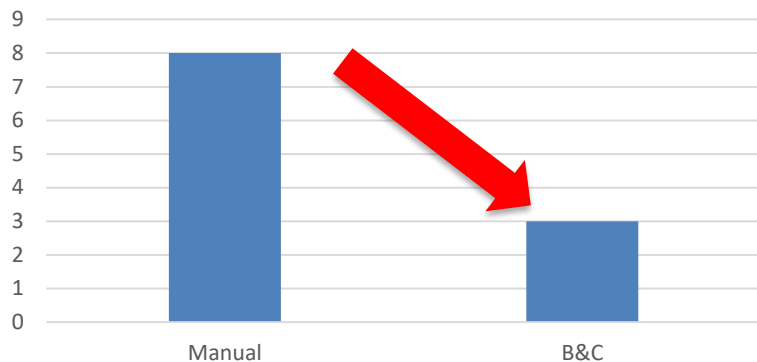
# Results and conclusions

## Some primarily results

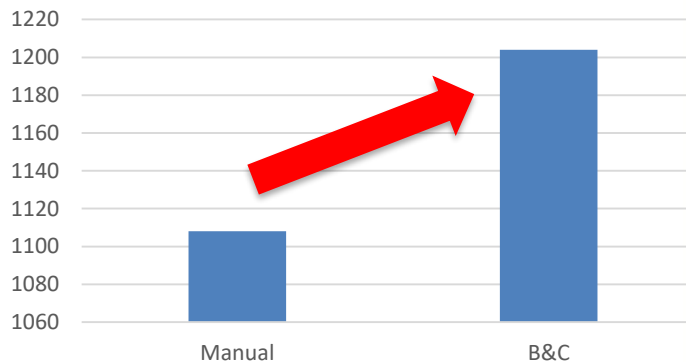


# Comparison with a human dispatcher

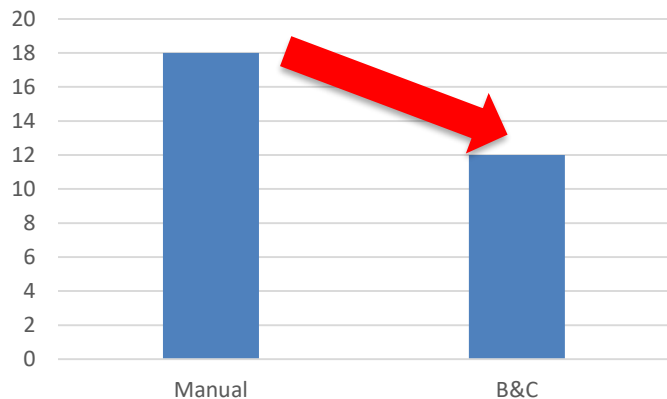
Cancelled services



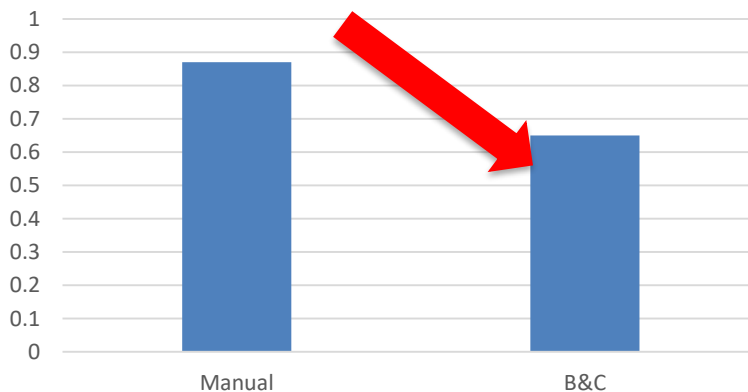
Delay time (sec)



Time (sec)



Weight cost



# Conclusions

- Our study first developed a path-based formulation for the integrated rolling stock and timetable rescheduling problem
- We developed a branch-and-price methodology for solving the path-based formulation more efficiently
- We developed a software for the decision-making of rail dispatchers
- Our methodology outperforms human dispatchers in computational time and the total weight cost



**Thanks!**  
**QA: [jtyin@bjtu.edu.cn](mailto:jtyin@bjtu.edu.cn)**

