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Integration of the Train and Rolling Stock Rescheduling For Metro System

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OUTLINE



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Urban Metro

> One of the most important means of transportation in China.

> By the end of 2019

40 Cities **6,730** kilometers



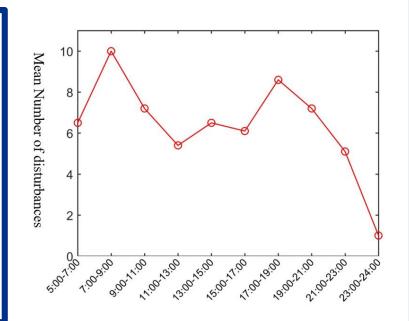






Disturbances

- > Infrastructure failures
- Equipment faults
- > Staff misoperation









The current way that metro system handles disturbances

Rescheduling

Rescheduling timetable manually Ordering

Calling the drivers and notifying the staff in the station

Recording

Recording the operation process







Present status of research

Urban metro train timetable rescheduling have attracted extensive attention due to

- short headway time
- uncertain passenger flow
- vulnerability to disturbances

Innovations of this research

Taking practical rescheduling means into account

- train operation strategy during the troubleshooting phase
- integration of train and rolling stock rescheduling

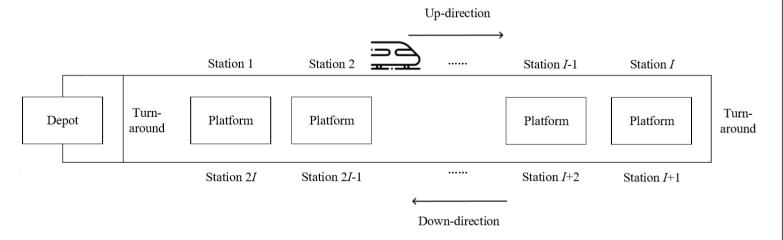






The considered structure of metro line

- \square Two running directions \square 2*I* stations
- ☐ One depot ☐ Some storage lines



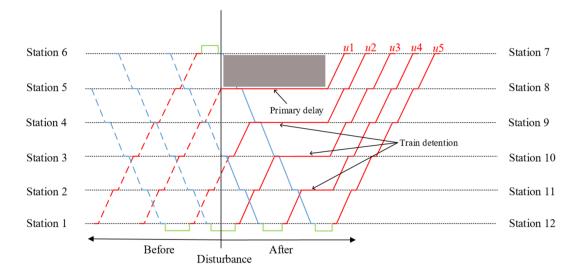






During the troubleshooting phase >

The dispatcher prefers to arrange trains to stop at stations during disturbances, which is defined as train detention.



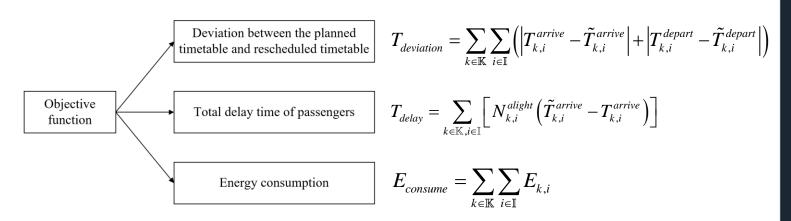






Objective Function >

$$\min Z = \omega_d T_{deviation} + \omega_t T_{delay} + \omega_e E_{consume}$$







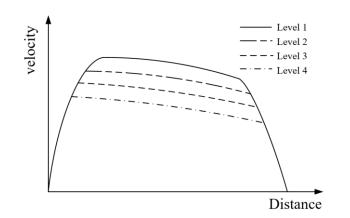


Constraints >

a) Running time constraints

$$ilde{T}_{k,i+1}^{ ext{arrive}} - ilde{T}_{k,i}^{ ext{depart}} = \sum_{l \in \mathbb{L}} \delta_{k,i}^l R_{k,i}^l$$

$$\sum_{l\in\mathbb{L}} \delta_{k,i}^l = 1$$



The running time between two consecutive stations is determined by preprogrammed speed profiles uniquely.







b) Dwelling time constraints

$$\tilde{T}_{k,i}^{ ext{depart}} - \tilde{T}_{k,i}^{ ext{arrive}} = \frac{N_{k,i}^{ ext{board}} + N_{k,i}^{ ext{alight}}}{\lambda}$$

 λ is the boarding/alighting speed of passengers.

c) Headway constraints

$$\left(\tilde{T}_{l,i}^{\text{arrive}} - \tilde{T}_{k,i}^{\text{depart}}\right) \mathcal{Y}_{k,l} \geq h_{\min}$$

 $\mathcal{Y}_{k,l}$ is the sequence indicator, =1 if train service *l* follows *k*.





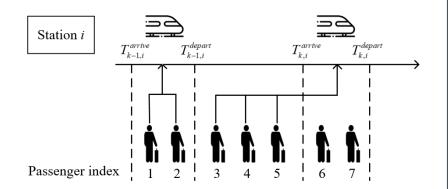


- d) Train capacity constraints
- Passenger OD matrix

$$P_{OD}(t) = \begin{pmatrix} p_{1,1}(t) & \cdots & p_{1,2I}(t) \\ \vdots & \ddots & \vdots \\ p_{2I,1}(t) & \cdots & p_{2I,2I}(t) \end{pmatrix}$$

$$N_{k,i} = N_{k,i-1} - N_{k,i-1}^{\text{arrive}} + N_{k,i-1}^{\text{board}} \le C$$

Passenger boarding and alighting process



$$T_{k,i}^{w} = \min \left\{ T_{k,i}^{depart}, \max \left\{ t \middle| C \ge N_{k,i-1} - N_{k,i}^{arrive} + \sum_{j=1}^{i-1} \int_{T_{k-1,j}}^{t} p_{j,i}(t) dt \right\} \right\}$$







e) Rolling stock circulation constraints

The train service *k* can be undertaken by two methods

turning around of online rolling stock

$$\left(T_{k,i}^{\mathrm{arrive}} - T_{l,i}^{\mathrm{depart}}\right) u_{k,l,i} \ge t_{\mathit{turn}}$$

 $u_{k,l,i}$ is the rolling stock succession indicator, =1 if train service k is executed after l by the same rolling stock







e) Rolling stock circulation constraints

coming out from the depot by backup rolling stock

$$\left(T_{k,i}^{\text{arrive}} - T_m^{\text{depart}}\right) z_{k,m,i} \ge t_{\text{online}}$$

 $z_{k,m,i}$ is the rolling stock usage indicator, =1 if train service k is executed by backup rolling stock







- f) Kinetic constraints
- \triangleright Basic resistance $R_0 + R_1 \cdot v_{k,i}^l(t) + R_2 \cdot v_{k,i}^l(t)^2$

ightharpoonup Slope resistance $M_{k,i}g \cdot \tan \theta_{k,i}(t)$

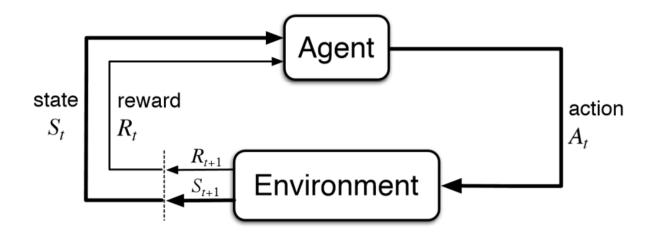
- ➤ Traction $F_{k,i}^l(t) = M_{k,i} \left(a_{k,i}^l(t) + g \cdot \sin \theta_{k,i}(t) \right) + R_0 + R_1 v_{k,i}^l(t) + R_2 v_{k,i}^l(t)^2$
- Energy consumption $E_{k,i} = \delta_{k,i}^l \int_0^{t_{k,i}^{l,a} + t_{k,i}^{l,c}} F_{k,i}^l(t) v_{k,i}^l(t) dt, \forall 1 \le k \le K, 1 \le i \le 2I$







Markov decision process









Markov decision process

The state variables for train at stations

The reward in each

stage determined by

the objective function.

State Action

Element definition

Reward Transition

The decision for train at stations

The change of state variables.







Algorithm >

> Action selection

 ε -greedy policy: With the probability ε , choose the action from the set of feasible actions randomly. With the probability $1-\varepsilon$, choose action by

$$a_i^n(k) = \arg\max_{a \in \mathbb{A}} Q(S_i^n(k), a_i^n(k)).$$







Algorithm >

> Value function update

Q-learning:

$$Q(S_t, A_t) \leftarrow Q(S_t, A_t) + \alpha \left[R_{t+1} + \gamma \max_{a} Q(S_{t+1}, a) - Q(S_t, A_t) \right]$$

 α is the learning rate γ is the discount factor

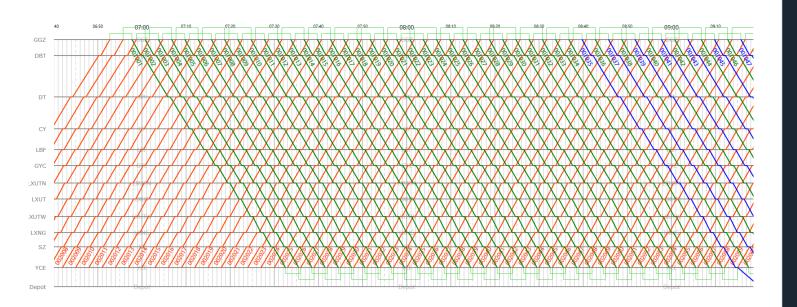




Case Study



Beijing Fangshan Metro Line



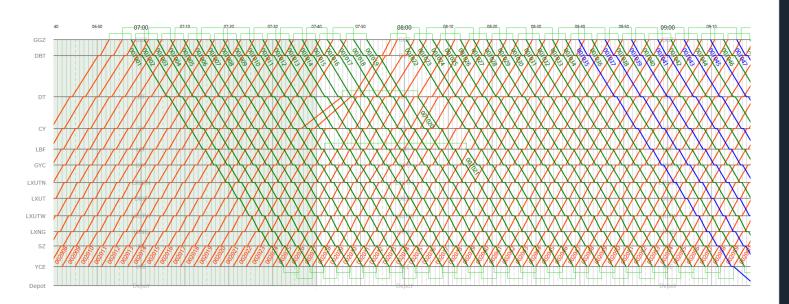




Case Study



Primary delay of 300s



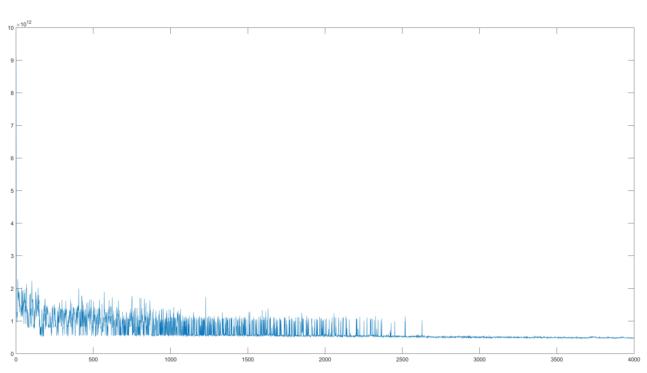




Case Study



Convergence process >







Conclusion



- By taking speed profiles in ATO system, time varying passenger flow into consideration, an integrated train and rolling stock rescheduling model is developed.
- an efficient algorithm based on Q-learning approach is designed.
- A tradeoff solution between operational cost and service quality can be generated within a short time.







Thank you for your attention!



