Mobility and Energy Impacts of Automated Cars

Analysis using MTC Travel Model One

Michael Gucwa - mgucwa@stanford.edu

2014 Automated Vehicle Symposium

Research Question

How will automation change the daily travel decisions of individuals and alter overall vehicle miles traveled and energy use?

What is the magnitude of the rebound effect from the reduce generalized cost of travel?

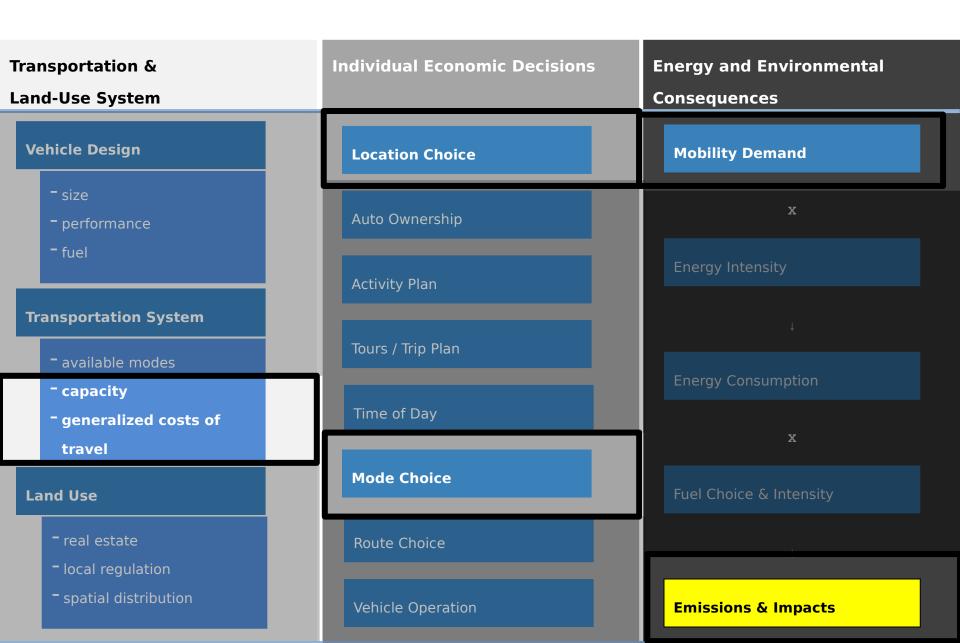
Scope of analysis

- Advanced Level 3 automation
 - O Vehicles must have driver present, but intervention rare
- Urban travel
 - O Do not consider impacts on intercity travel
- Status quo for vehicle ownership and form
 - O No shared economy or drastic changes to vehicle design

Potential energy pathways

Transportation & Land-Use System	Individual Economic Decisions	Energy, Economic, & Environmental Impacts
Vehicle Design	Location Choice	Mobility Demand
- size - performance - fuel Transportation System - available modes - capacity - generalized costs of travel	Auto Ownership	x
	Activity Plan	Energy Intensity
	Tours / Trip Plan	↓ Energy Consumption
	Time of Day	x
Land Use	Mode Choice	Fuel Choice & Intensity
real estate local regulation	Route Choice	1
- spatial distribution	Vehicle Operation	Emissions & Impacts

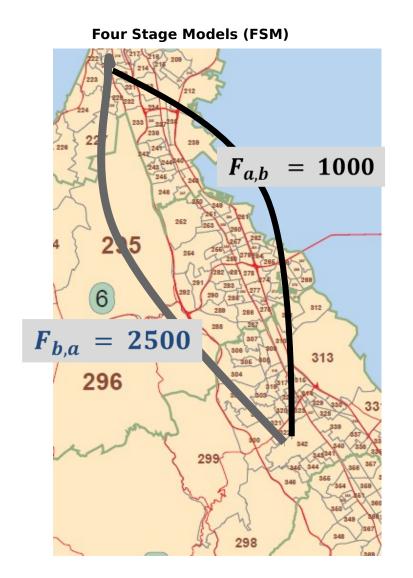
Research Focus



Methodology

- Model automated vehicle scenarios using San Francisco's Metropolitan
 Commission's *Travel Model One*
- Simulate the microeconomic travel decisions for every person in the 9 county San Francisco Bay Area
- Use activity-based model approach (ABA)
- Each decision follows a random utility model

Brief Discussion of Transport Models

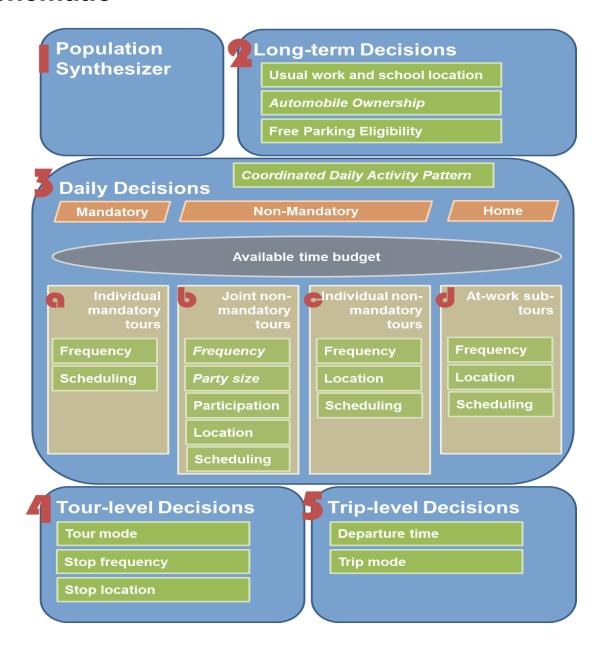




Travel Model One Logical Overview

2 **Population Synthesizer Network Warm Start** Economic starting conditions Transport system starting conditions 4 CT-RAMP Citilabs Cube Individual level microeconomic decisions Transportation network model Loop for convergence: 3+ iterations Output Processing: Cube, EMFAC, SAS, Excel, R

CT-RAMP Schematic



Random Utility Model

$$U_{i,j} = V_{i,j}(X_{i,j} \mid \beta_{i,j}) + \epsilon_{i,j}$$

- Person i is choosing among discrete alternatives J (do I drive or walk)
- V is the deterministic (or representative) utility
- X is the observable factors (individual and alternative attributes)
- β estimated (or assumed) coefficient parameters.
- $\epsilon_{i,j}$ -A random term to capture the effect of unobserved attributes and the idiosyncratic preference person i has for alternative j

Model Modifications1

- Create scenarios on two primary dimensions:
 - 1. Value of in-vehicle time
 - 2. Roadway capacity
- Value of time
 - V_{i,o,d,m}=c.ivt_m•ivt_{o,d,m}+c.cost_m•cost_{o,d,m} + (other terms)
 - i = person, o = origin, d = destination, m = travel mode
 - c.ivt = utility coefficient on travel time, ivt = travel time, c.cost = utility coefficienton \$ costs, cost = \$
 - We change the coefficient for automated vehicles
 - Affects dozens of decisions for each of millions of individuals
- Capacity
 - Change capacity / speed relationship in Citilabs transport network representation

Scenarios

Model scenarios considered		Roadway Capacity		
		(B) - Base	(L) - Low Base + 10%	(H) - High Base + 100%
In Vehicle Value of Time	(B) - Base	BB	-	ВН
	(H) - High quality rail	-	HL	НН
	(L) - ½ current car	-	LL	LH
	(0) - Zero time cost	0B	-	ОН

Results

 With automation can expect a short-run increase of 4-8% in daily vehicle miles travelled

Vehicle Miles Traveled % Change from Base Case		Roadway Capacity		
		Base (B)	Low (L) + 10%	High (H) + 100%
(B) Base (H) High quality rail Value of Time (L) ½ current car (0) Zero time cost	(B) Base	0%	-	+2.0%
	(H) High quality rail	-	+4%	+5.2%
	(L) ½ current car	-	+6.7%	+7.9%
	(0) Zero time cost	+13.2%	-	+14.5%

The unanswered questions...

- Long-term land-use adjustments
- Welfare and equity
- The role of policy
- Level 4 and shared economy (robotaxis)

Thank you!

mgucwa@stanford.edu