

A Seasonality Diagnostic Based Upon Multi-Step Ahead Forecasting Errors

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Outline

- Seasonality diagnostics motivation
- Heuristics: seasonal persistence and intra-seasonal association
- Seasonality measures defined
- Illustrations



Overview

Seasonality is present in many regularly-spaced economic time series

Statistical agencies seek to identify and remove (seasonally adjust) the seasonality, so as to allow easier visualization of trends and cycles

Challenge: how to define (or measure) seasonality? What diagnostic corresponds to our definition?



Available diagnostics

There are many diagnostics available, each based on a certain definition of seasonality:

- Model-based F (MBF): test of seasonal means in a linear model with time series errors
- QS: seasonal lag autocorrelation
- Visual Significance (VS): peak in spectral density at seasonal frequency
- Root: seasonal roots in autoregressive polynomial



Critique

1. These diagnostics cannot be defined without first postulating a form of process: RegARIMA for MBF, difference stationary for QS and VS, autoregressive for Root.
2. These diagnostics assess different types of seasonality: fixed for MBF, dynamic for QS and VS and Root.
3. These diagnostics may classify non-seasonal processes as seasonal: e.g., QS.
4. These diagnostics are not easily conveyed to non-experts.



Goal

Define a new seasonality measure (and diagnostic) with these features:

- Intuitive definition that is broad, such that when specialized to familiar processes (e.g., difference stationary, RegARIMA, autoregressive) they have expected behavior on seasonal and non-seasonal processes.
- Avoids classification problems by incorporating both **seasonal persistence** and **intra-seasonal association**.
- Should be scale-free.



Problem with seasonal autocorrelation

Let s be the integer seasonal period.

Intuitively, a high association between observations s lags apart is necessary to describe seasonality.

For a stationary process, this would be measured with the lag s autocorrelation.

But: for the AR(1) process, which is non-seasonal, the lag s autocorrelation is ϕ^s . For $s = 4$ and $\phi = .95$, this yields .815, a high value – a mis-classification.



Modifying seasonal autocorrelation

The AR(1) case is instructive: the seasonal autocorrelation is really driven by the high lag 1 autocorrelation, as season-to-season there is a high association.

We should *condition* on this **intra-seasonal association**, to balance seasonal persistence.

Consider the seasonal sub-series (i.e., annual time series for each season); if these have a similar pattern, then we say there is intra-seasonal association.



Seasonal persistence

Let $\{X_t\}$ be our time series. We first define **seasonal persistence** by modifying the seasonal autocovariance slightly: we condition on the recent past (denoted by $\{X_{t:}\}$), which isolates current observations. The seasonal persistence is defined as

$$\Xi_s = \text{Cov}[X_{t+s+1}, X_{t+1} | X_{t:}]. \quad (1)$$

The conditioning removes time-dependence from the measure for many processes, since (1) can be expressed as the covariance of $s + 1$ -step ahead and 1-step ahead forecast errors.



Intra-seasonal association

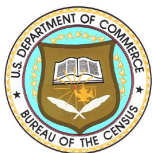
Intra-seasonal association is measured by the s -step ahead forecast error

$$X_{t+s} - \hat{X}_{t+s|t},$$

since this will tend to be large when the seasonal sub-series are tightly linked.

But intra-seasonal association can be high whether or not the process has seasonality.

If the process is seasonal, intra-seasonal association should be low.



Seasonal measures

We can account for intra-seasonal association in the seasonal persistence measure by introducing conditioning upon the s -step ahead forecast error, or (equivalently)

$$\Omega_s = \text{Cov}[X_{t+s+1}, X_{t+1} | X_{t+s}, X_{t:}].$$

It is straightforward to show that

$$\Omega_s = \Xi_s - \text{Cov}[X_{t+s+1}, X_{t+s} | X_{t:}] \text{Var}[X_{t+s} | X_{t:}]^{-1} \text{Cov}[X_{t+s}, X_{t+1} | X_{t:}]$$

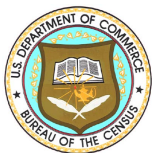


Normalized form

Because Ω_s is not scale invariant, we can also consider the partial correlation:

$$\begin{aligned}\Upsilon_s &= \text{Corr}[X_{t+s+1}, X_{t+1} | X_{t+s}, X_{t:}] \\ &= \frac{\Omega_s}{\sqrt{\text{Var}[X_{t+s+1} | X_{t+s}, X_{t:}] \text{Var}[X_{t+1} | X_{t+s}, X_{t:}]}}.\end{aligned}$$

This gives a seasonality measure with values in $[-1, 1]$, with 0 indicating no seasonality, and positive values indicating moderate to high degrees of seasonality. Negative values are designated as *anti-seasonality*.



Stationary forecast errors

For many classes of processes the forecast errors will be stationary (jointly across leads), and hence

$$v_h^{(k)} = \text{Cov}[X_{t+k}, X_{t+h+k} | X_{t:}]$$

does not depend on t . Then

$$\Omega_s = v_s^{(1)} - v_{s-1}^{(1)} v_1^{(s)} / v_0^{(s)}$$

$$\Upsilon_s = \frac{v_s^{(1)} - v_{s-1}^{(1)} v_1^{(s)} / v_0^{(s)}}{\sqrt{(v_0^{(1)} - v_{s-1}^{(1)2} / v_0^{(s)}) (v_0^{(s+1)} - v_1^{(s)2} / v_0^{(s)})}}.$$



Difference stationary processes

We say $\{X_t\}$ is difference stationary if there exists a unit root polynomial $\delta(z)$ such that $\delta(B)X_t = W_t$ is stationary, say with MA (∞) representation $W_t = \psi(B)Z_t$, with $\{Z_t\}$ white noise of variance σ^2 and $\psi(z)$ causal. (B is the backshift operator.) Then forecast errors are stationary, and

$$v_h^{(k)} = \sigma^2 \sum_{\ell=0}^{k-1} \xi_\ell \xi_{\ell+h},$$

where $\xi(z) = \psi(z)/\delta(z)$. Also

$$\Omega_s = \sigma^2 \left(\xi_s - \xi_{s-1} \sum_{\ell=0}^{s-1} \xi_\ell \xi_{\ell+1} / \sum_{\ell=0}^{s-1} \xi_\ell^2 \right).$$



AR(1) process

$\{X_t\}$ is an AR(1), so that $\psi(z) = (1 - \phi z)^{-1}$ and $\xi_j = \psi_j = \phi^j$:

$$\Xi_s = \sigma^2 \phi^s$$

$$\Omega_s = \sigma^2(\phi^s - \phi^{s-1}\phi) = 0.$$

So there is no seasonality present once the intra-seasonal association is accounted for.



Cyclic AR(2) process

$\{X_t\}$ is an AR(2) with complex conjugate seasonal roots: $\psi(z) = (1 - 2\rho \cos(\omega)z + \rho^2 z^2)^{-1}$, which corresponds to autoregressive roots $\rho^{-1} \exp\{\pm i\omega\}$ (for $0 < \rho < 1$), where $\omega = 2\pi\ell/s$ for some integer ℓ . Then $\xi_j = \psi_j = \rho^j \cos(\omega j)$, and

$$\Xi_s = \sigma^2 \rho^s$$

$$\Omega_s = \sigma^2 \rho^s \left(1 - \cos(\omega) \sum_{\ell=0}^{s-1} \rho^{2\ell} [\cos(\omega(2\ell+1)) + \cos(\omega)] / \sum_{\ell=0}^{s-1} \rho^{2\ell} [\cos(\omega(2\ell)) + 1] \right)$$

Setting $s = 4$, $\Upsilon_4 = .326$ for $\rho = .8$, and $\Upsilon_4 = .454$ for $\rho = .9$. Therefore, such a process exhibits seasonality.



SAR(1) process

$\{X_t\}$ is a seasonal autoregression of order 1 (or SAR(1)), so that $\psi(z) = (1 - \phi_s z^s)^{-1}$. So $\xi_j = \psi_j$ is zero unless $j = sk$ for integer k , in which case $\xi_j = \phi_s^k$. Then

$$\Xi_s = \sigma^2 \phi_s$$

$$\Omega_s = \sigma^2 \phi_s$$

$$\Upsilon_s = \phi_s / \sqrt{1 + \phi_s^2}.$$

The maximum value of Υ_s for this process is $1/\sqrt{2}$.



Seasonal difference process

$\{X_t\}$ is a SARIMA process with differencing polynomial $\delta(z) = 1 - z^s$, so that $\xi(z) = \psi(z) + z^s\psi(z) + \dots$. Then

$$\Xi_s = \sigma^2(\psi_s + 1)$$

$$\Omega_s = \sigma^2 \left(1 + \psi_s - \psi_{s-1}(\psi_{s-1} + \sum_{\ell=0}^{s-1} \psi_\ell \psi_{\ell+1}) / \sum_{\ell=0}^{s-1} \psi_\ell^2 \right).$$



Seasonal difference process

Further, if $\psi(z) = 1 - \theta_s z^s$, then

$$\Xi_s = \Omega_s = \sigma^2(1 - \theta_s)$$

$$\Upsilon_s = (1 - \theta_s) / \sqrt{1 + (1 - \theta_s)^2}.$$

As θ_s approaches 1, the nonstationary process resembles a white noise (due to cancellation of operators), and the seasonality measure tends to zero. If instead $\theta_s \rightarrow -1$, then $\Upsilon_s \rightarrow 2/\sqrt{5}$, which is a higher value than that attainable by the SAR(1).



Seasonal and regular difference process

$\{X_t\}$ is a SARIMA process with differencing polynomial $\delta(z) = (1 - z^s)(1 - z)$. Letting $U(z) = 1 + z + \dots + z^{s-1}$, we find that $\xi(z) = \psi(z)U(z) + 2z^s\psi(z)U(z) + \dots$. It follows that

$$\Xi_s = \sigma^2(2 + \sum_{k=1}^s \psi_k).$$



Airline process

For the airline process $\psi(z) = (1 - \theta_1 z)(1 - \theta_s z^s)$, so that

$$\Xi_s = \sigma^2(2 - \theta_1 - \theta_s)$$

$$\Omega_s = \sigma^2 \left((2 - \theta_1 - \theta_s) \left[\frac{1 + (s - 2)(1 - \theta_1)^2}{1 + (s - 1)(1 - \theta_1)^2} \right] - (1 - \theta_1)^2 \left[\frac{1 + (s - 2)(1 - \theta_1)}{1 + (s - 1)(1 - \theta_1)^2} \right] \right).$$

So high positive values of θ_s lessen the seasonal persistence. Also, positive values of θ_1 tend to increase seasonality, up to a point, by decreasing the intra-seasonal association. See Figures 1 and 2 for the case of $s = 4$.



Airline process

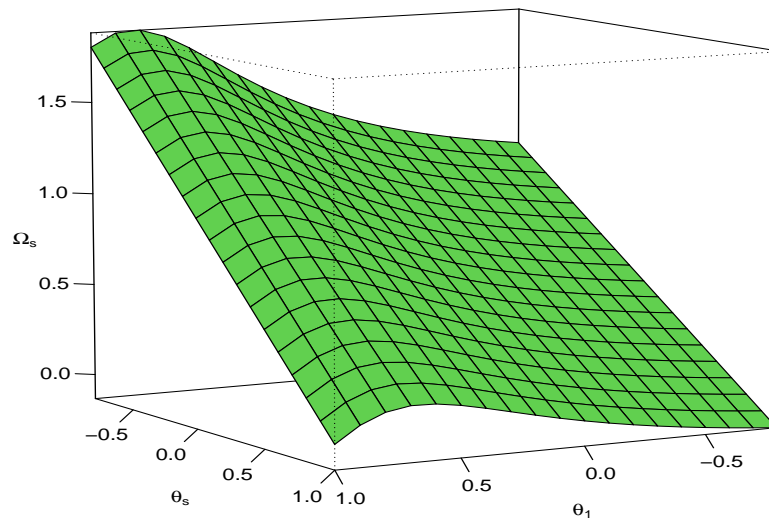


Figure 1: Values of Ω_4 for an airline process, as a function of θ_1 and θ_s .



Airline process

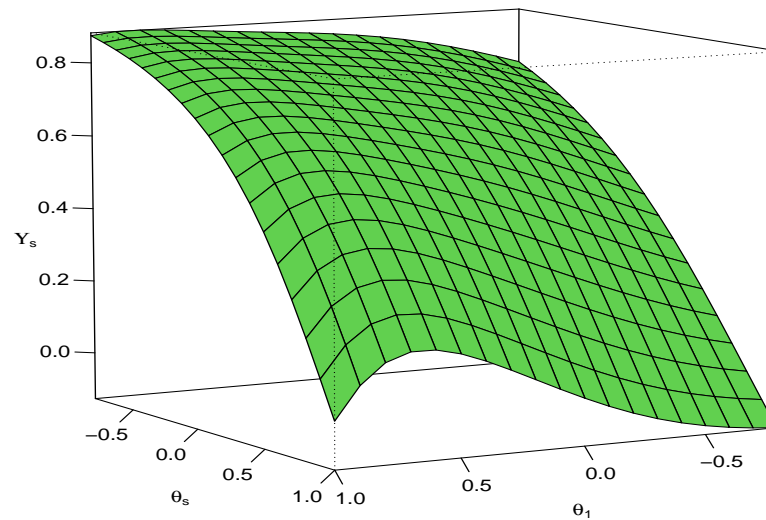


Figure 2: Values of Υ_4 for an airline process, as a function of θ_1 and θ_s .



Seasonal Roots

We can analyze ARIMA processes via the roots of its autoregressive polynomial:

- Seasonal persistency Ξ_s is driven by AR roots with near-unit magnitude and seasonal frequency (argument is a multiple of $2\pi/s$)
- Intra-seasonal association is high when a reciprocal root is strong and close to the lag one autocorrelation



Other Diagnostics

The seasonality measures can be connected to VS, Root, and QS.

- Spectral peaks occur at frequencies associated with the argument of AR roots with modulus close to one. So Ω_s is connected to Root and VS diagnostics.
- For ARIMA processes a large value of Ω_s indicates a large lag s autocorrelation, so the QS measure will be large; conversely, QS can be large due to high intra-seasonal association (e.g., AR(1)) even when Ω_s is small.



Inference

We can estimate Ω_s and Υ_s by replacing covariances of forecast errors by sample covariances of such, computed in-sample.

A CLT for both estimators has been derived, but the asymptotic variance depends on quantities not determined by the null hypothesis.

Testing: we may wish to test the null hypothesis $\Omega_s = 0$, which is equivalent to $v_s^{(1)}v_0^{(s)} - v_{s-1}^{(1)}v_1^{(s)} = 0$.



Testing

Consider the estimator

$$\hat{\theta}_T = \hat{v}_s^{(1)} \hat{v}_0^{(s)} - \hat{v}_{s-1}^{(1)} \hat{v}_1^{(s)},$$

which tends to zero if $\Omega_s = 0$. This has a CLT with unknown variance, so we propose studentizing by some S_T (based on partial sums of forecast error cross-products) and obtain ($\{B_r\}$ is standard Brownian Motion)

$$T^{1/2} \frac{\hat{\theta}_T - \mu_Z}{\sqrt{S_T}} \xrightarrow{\mathcal{L}} \frac{2B_1}{\sqrt{\int_0^1 (B_r - rB_1)^2 dr}}.$$



Numerical Results

We simulate 10^4 draws of a quarterly SAR(1) process with $\phi_s = .8$ and unit innovation variance, for which $\Omega_s = .8$.

To illustrate the size properties, we center the statistic by $\mu_Z = .8$ (first column), and for power properties we set $\mu_Z = 0$ (second column).



Numerical Results

Table 1: Upper one-sided rejection rates for studentized seasonal measure test statistic applied to a SAR(1) with $\phi_s = .8$, by number of years n , nominal level α , and centering by μ_Z .

n	α	$\mu_Z = .8$	$\mu_Z = 0$
$n = 20$.01	.005	.541
	.05	.031	.883
	.10	.081	.976



Summary

- Seasonality is defined as seasonal persistence that is not explained by intra-seasonal association
- Seasonal persistence is defined as lag s covariance conditional on the past
- Intra-seasonal association is defined as lead s forecast error
- Ξ_s measures seasonal persistence, Ω_s measures seasonal persistence conditional on intra-seasonal association, and Υ_s is a normalized Ω_s
- These measures have desired values on various SARIMA processes; correct classification



Future work

- Investigate seasonality measures on seasonally heteroscedastic processes and stochastic seasonal means (including RegARIMA) processes
- Explore the impact of seasonal adjustment on seasonality measures
- Empirical testing



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